

inverse de $a \in \mathbb{P}_{A_2}$ mod $p = [A_3]$
mod $v(x) = [A_4]$

pose $b \in \mathbb{P}_{A_2}$ a l'abri tel que $ab \equiv 1 \pmod{p}$
 $\pmod{v(x)}$
 $\deg(b) < \deg(v)$

[Algorithm d'Euclide étendu Knuth p325]

répète
XMINV

```
XMPINV: MOVE.L A3, -(SP)
```

```
MOVE.L A6, -(SP) u1 = 1
```

```
BSR XPSP1
```

```
MOVE.L A/A6, -(SP) } u3 ≡ a mod p
```

```
BSR XMPPM
```

```
MOVE.L (SP)+, A0
```

```
MOVE.L A6, -(SP) } v1 = 0
```

```
BSR XPSP0
```

```
MOVE.L A6, -(SP) } v3 ≡ v(x) mod p
```

```
BSR XMPPM
```

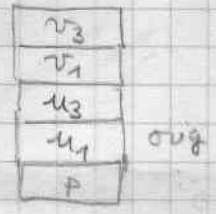
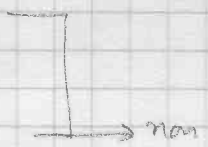
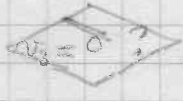
```
MIG0: MOVE.L (SP), A1 v3
```

```
TST.L (A1)
```

```
BNE MIG2
```

```
CMP # $4000, 4(M)
```

```
BNE MIG2
```



```
fin ADDQ # 8, SP  
MOVE.L (SP)+, A6  
MOVE.L (SP)+, A2/A3
```

vérif que le pgcd(a, v(x)) = ~~ste~~ ≠ 0

```
TST.L (A6)
```

```
BNE ERDVD → pg non
```

```
CMP # $4000, 4(A6)
```

```
BEQ ERDVD → pgcd = 0
```

```
RTS
```

fin

```

ADDQ #4, SP
MOVE.L (SP)+, A6
MOVE.L (SP)+, A0      u3
TST.L (A0)+
BNE  ERRDV           u3 ≠ cte
MOVE.L 4(SP), A1     P

```

```

BSR  XMINVS           u3-1
  MOVEM.L (SP), A0/A3  u1 P
  MOVE.L A2, A1        u3-1

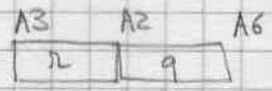
```

```

BRA  MIG90           met u1 u3-1

```

MI92: MOVEM.L 8(SP), A0/A2/A3 ^{u3 x P}



BSR XMPDIV

MOVE.L A3, -(SP) $r = t_3$

MOVE.L A2, A0 q

MOVE.L 8(SP), A1 v_1

MOVE.L 20(SP), A3 p

BSR XMPMUL qv_1 conserve A3

MOVE.L A2, A1

MOVE.L 16(SP), A0 u_1

BSR XMPSUB $t_1 = u_1 - qv_1$ conserve A3

MOVE.L (SP), A0 t_3

MOVE.L A2, -(SP)

BSR XPSAP recopie $t_3 = r$

MOVEM.L A2/A6, -(SP)

MOVEM.L 16(SP), A0/A2/A3/A6 $v_3 v_1 u_3 u_1$

EXG A0, A6

BSR XLB76 copie nouveau u_1 (ex v_1)

MOVE.L A6, 24(SP)

MOVE.L 12(SP), A6 fin de v_3

BSR XLB76 copie nouveau u_3

MOVE.L A6, 20(SP) nouveau v_1

MOVE.L (SP)+, A6 $t_3 = \text{fin } t_1$

MOVE.L (SP)+, A1 fin t_3

MOVE.L (SP)+, A2 t_1

BSR XLB76 copie nouveau $v_1 = t_1$

ADDQ #8, SP nouveau v_3

MOVE.L A6, -(SP) fin t_3

BSR XLB76 copie nouveau v_3

BRA MI90