

entrée  $\langle A_0 \rangle_x$ ,  $\langle A_1 \rangle_y$

sortie  $\langle A_2 \rangle = \text{angle}(x, y) = \text{atan2}(y, x) \in ]-\pi, \pi]$

XFFANG: CPVPRG2 XFFANG vérif

TT \ XFFANG: if flag30

JSR CPCVI2 (30)43 met FP0, FP1

BNE ST \ XFFANG

JSR CPCANG (30)78 FP2 = angle(FP0, FP1)

FMOVE FP2, FP0

FBOR CPCVF → pose FP0

endif

ST \ XFFANG: